



# NONPARAMETRIC INFERENCE ON DOSE-RESPONSE CURVES WITHOUT THE POSITIVITY CONDITION

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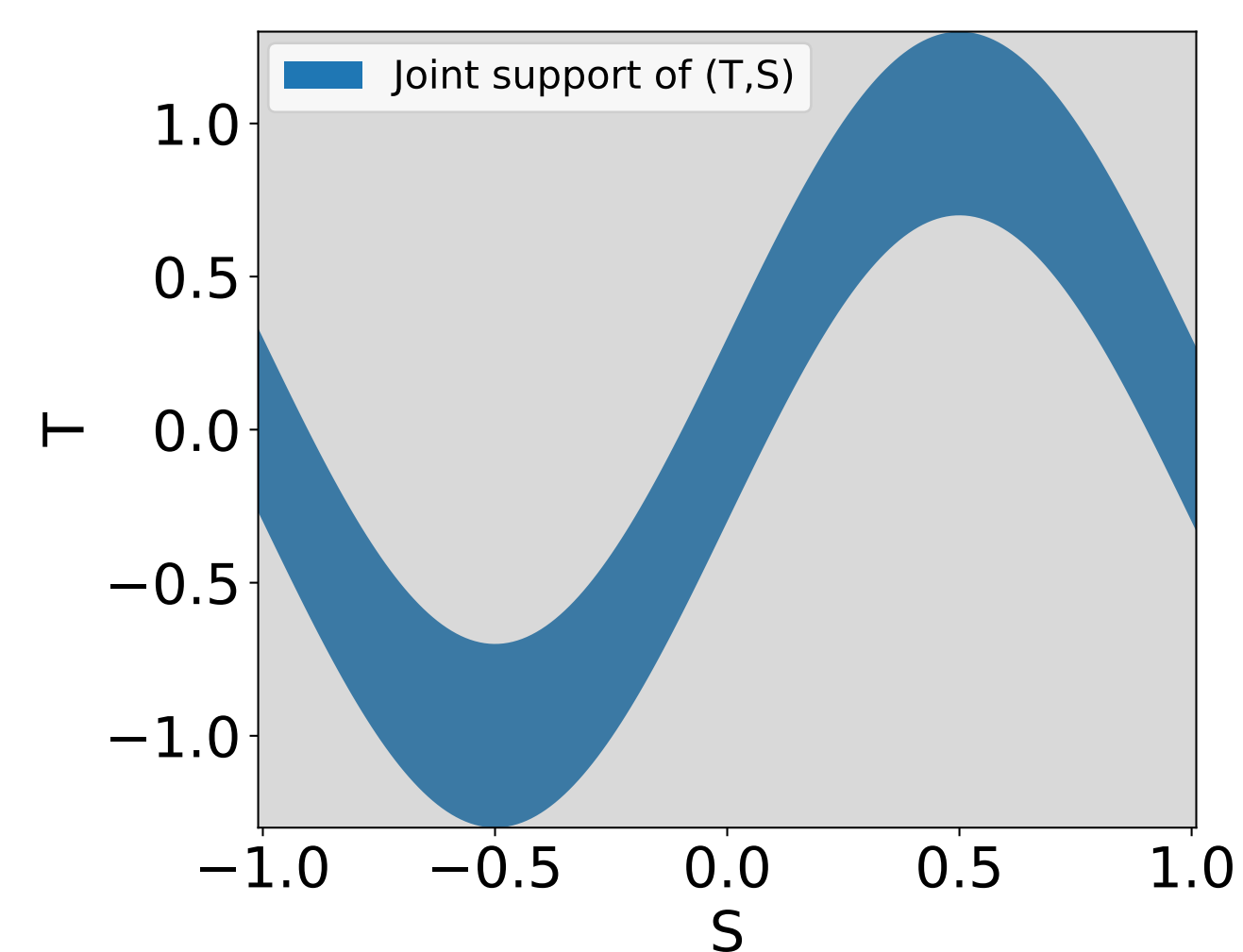


## INTRODUCTION

Estimating the causal effects for continuous treatments (*i.e.*, the dose-response curves) often relies on the **positivity condition**:

*Every subject has some chance of receiving any treatment level  $T = t$  regardless of its covariates  $\mathbf{S} = \mathbf{s} \in \mathbb{R}^d$ .*

- This condition **could fail** in observational studies with continuous treatments.



- We propose a novel integral estimator of the dose-response curve without assuming the positivity condition.

- It is based on a localized derivative estimator and the fundamental theorem of calculus.
- It can be efficiently computed in practice via Riemann sum approximations.
- It can be combined with bootstrap methods for valid inference on the dose-response curve and its derivative.

## IDENTIFICATION CONDITIONS

Assume that  $\{(Y_i, T_i, \mathbf{S}_i)\}_{i=1}^n$  are IID from the model:

$$Y = \mu(T, \mathbf{S}) + \epsilon \quad \text{and} \quad T = f(\mathbf{S}) + E,$$

where  $E \perp\!\!\!\perp \mathbf{S}$ ,  $\epsilon \perp\!\!\!\perp \mathbf{S}$ ,  $\mathbb{E}(E) = \mathbb{E}(\epsilon) = 0$ ,  $\mathbb{E}(E^2) > 0$ , and  $\mathbb{E}(\epsilon^4) < \infty$ .

**Dose-response curve** and its **derivative function** can be identified with observed data as:

$$m(t) = \mathbb{E}[\mu(t, \mathbf{S})] \quad \text{and} \quad \theta(t) = m'(t) = \frac{d}{dt} \mathbb{E}[\mu(t, \mathbf{S})]$$

under *consistency* and *ignorability* assumptions.

**Interchangability Assumption:** The function  $\mu(t, \mathbf{s})$  is continuously differentiable with respect to  $t$  and

$$\mathbb{E}[\mu(T, \mathbf{S})] = \mathbb{E}[m(T)],$$

$$\theta(t) = \mathbb{E}\left[\frac{\partial}{\partial t} \mu(t, \mathbf{S})\right] = \mathbb{E}\left[\frac{\partial}{\partial t} \mu(t, \mathbf{S}) \mid T = t\right].$$

## MOTIVATING EXAMPLE

Consider the following additive confounding model:

$$Y = m(T) + \eta(\mathbf{S}) + \epsilon \quad \text{and} \quad T = f(\mathbf{S}) + E$$

with  $\mathbb{E}[\eta(\mathbf{S})] = 0$ . This model satisfies our interchangability assumption and is known as the geoadaptive structural equation in spatial statistics.

## THREE KEY INSIGHTS

- $\mu(t, \mathbf{s})$  and  $\frac{\partial}{\partial t} \mu(t, \mathbf{s})$  can be consistently estimated at each observation  $(T_i, \mathbf{S}_i)$ .
- $\theta(t)$  can be consistently estimated by the localized form  $\theta_C(t) = \mathbb{E}\left[\frac{\partial}{\partial t} \mu(t, \mathbf{S}) \mid T = t\right]$ .
- By the fundamental theorem of calculus,

$$m(t) = m(T) + \int_{\tilde{t}=T}^{\tilde{t}=t} m'(\tilde{t}) d\tilde{t} = m(T) + \int_{\tilde{t}=T}^{\tilde{t}=t} \theta(\tilde{t}) d\tilde{t}.$$

$\Rightarrow$  Taking the expectation on both sides yield that

$$\begin{aligned} m(t) &= \mathbb{E}[\mu(T, \mathbf{S})] + \mathbb{E}\left[\int_{\tilde{t}=T}^{\tilde{t}=t} \theta_C(\tilde{t}) d\tilde{t}\right] \\ &= \mathbb{E}(Y) + \mathbb{E}\left[\int_{\tilde{t}=T}^{\tilde{t}=t} \theta_C(\tilde{t}) d\tilde{t}\right]. \end{aligned}$$

## PROPOSED ESTIMATORS

**Proposed Integral Estimator of  $m(t)$ :**

$$\hat{m}_\theta(t) = \frac{1}{n} \sum_{i=1}^n \left[ Y_i + \int_{\tilde{t}=T_i}^{\tilde{t}=t} \hat{\theta}_C(\tilde{t}) d\tilde{t} \right],$$

where  $\hat{\theta}_C(t)$  is a consistent estimator of  $\theta_C(t) = \int \beta_2(t, \mathbf{s}) dP(\mathbf{s} | t)$  with  $\beta_2(t, \mathbf{s}) \equiv \frac{\partial}{\partial t} \mu(t, \mathbf{s})$ .

- Fit  $\beta_2(t, \mathbf{s})$  by local polynomial regression;
- Estimate  $P(\mathbf{s} | t)$  by Nadaraya-Watson conditional CDF estimator.

**Proposed Localized Estimator of  $\theta(t)$ :**

$$\hat{\theta}_C(t) = \frac{\sum_{i=1}^n \hat{\beta}_2(t, \mathbf{S}_i) \cdot \bar{K}_T\left(\frac{T_i - t}{h}\right)}{\sum_{j=1}^n \bar{K}_T\left(\frac{T_j - t}{h}\right)}.$$

## FAST COMPUTING ALGORITHM

Let  $T_{(1)} \leq \dots \leq T_{(n)}$  be the order statistics of  $T_1, \dots, T_n$  and  $\Delta_j = T_{(j+1)} - T_{(j)}$  for  $j = 1, \dots, n-1$ .

- Approximate  $\hat{m}_\theta(T_{(j)})$  for  $j = 1, \dots, n$  as:

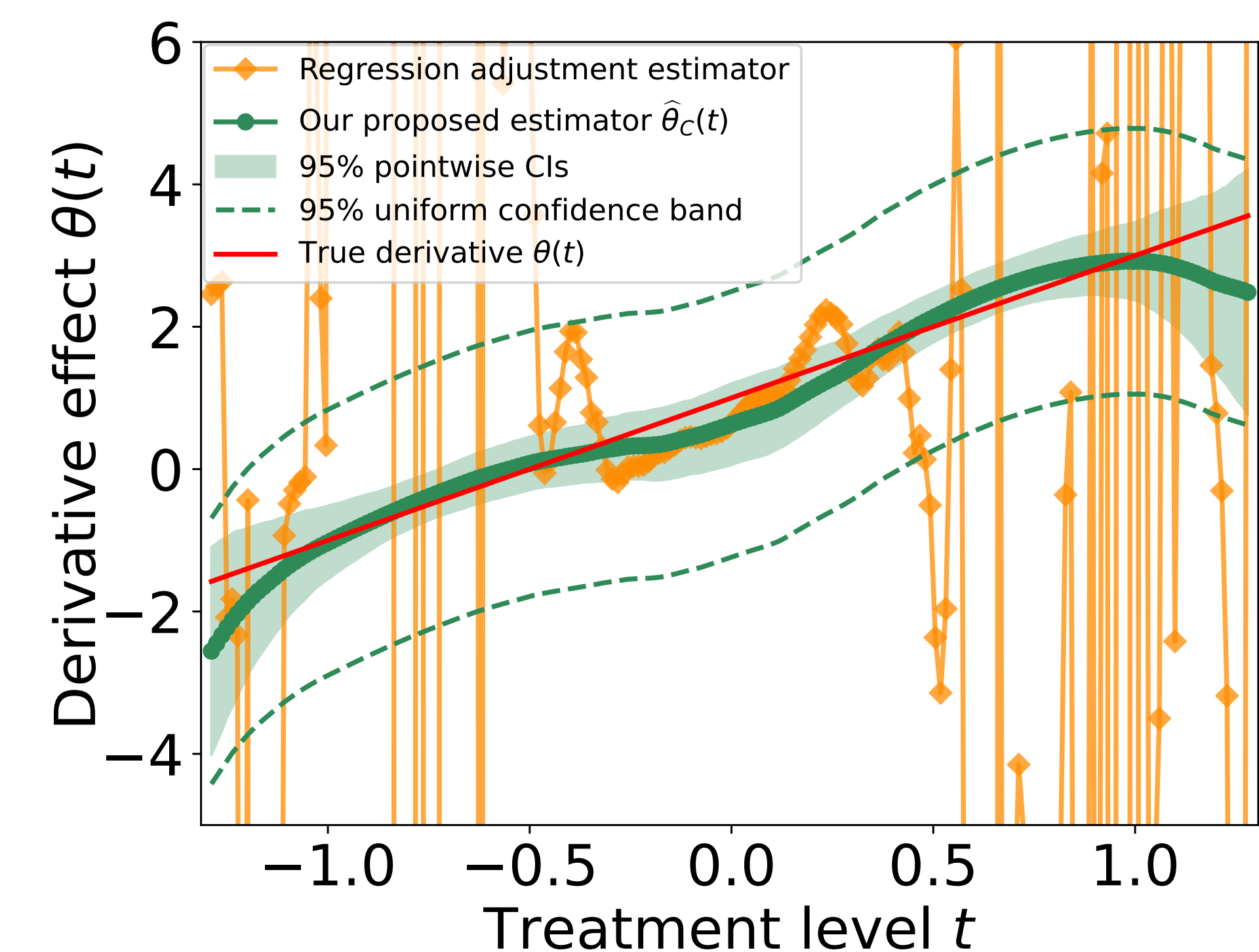
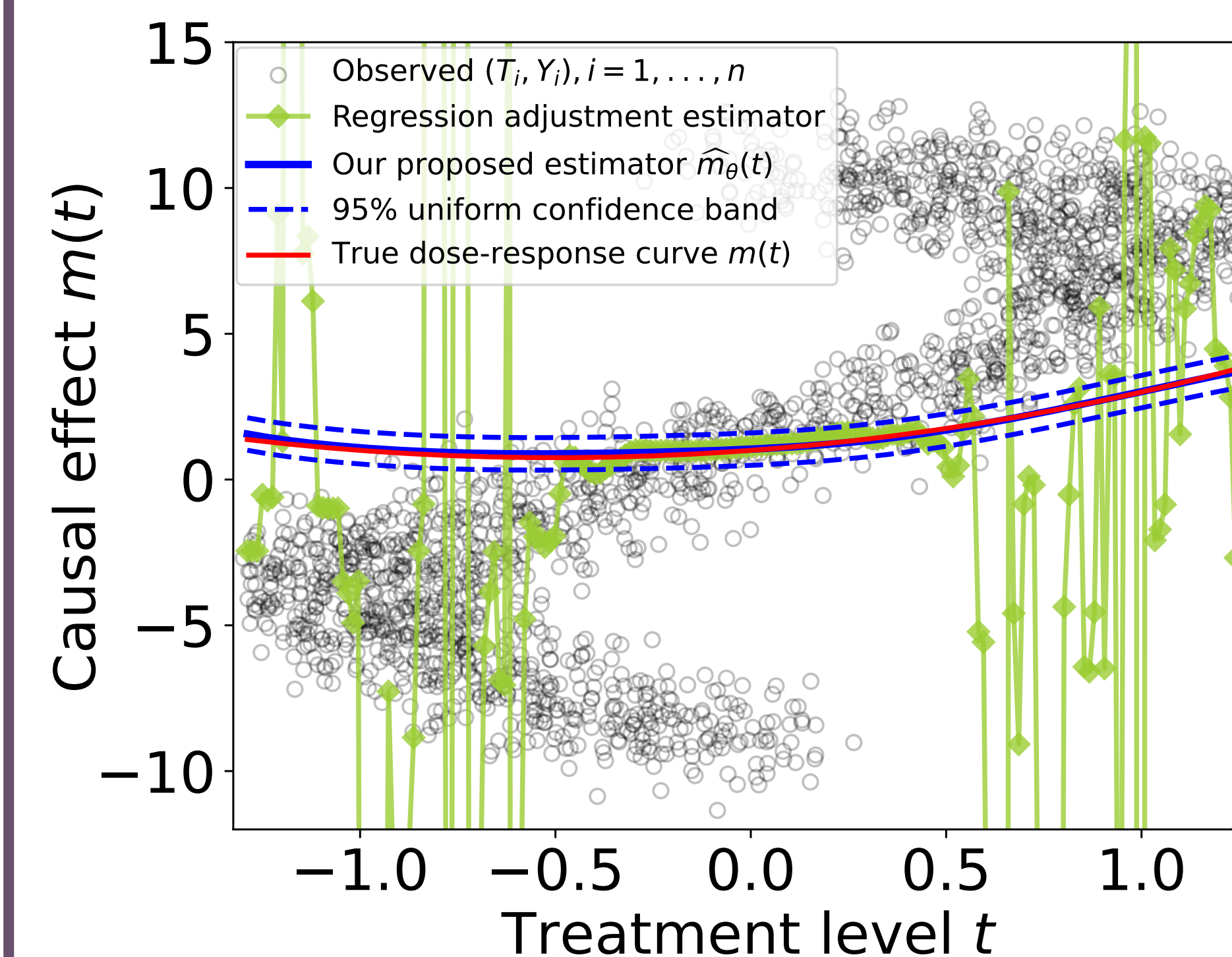
$$\begin{aligned} \hat{m}_\theta(T_{(j)}) \approx & \frac{1}{n} \sum_{i=1}^n Y_i + \frac{1}{n} \sum_{i=1}^{n-1} \Delta_i \left[ i \cdot \hat{\theta}_C(T_{(i)}) \mathbb{1}_{\{i < j\}} \right. \\ & \left. - (n-i) \cdot \hat{\theta}_C(T_{(i+1)}) \mathbb{1}_{\{i \geq j\}} \right]. \end{aligned}$$

- Evaluate  $\hat{m}_\theta(t)$  at any  $t \in [T_{(j)}, T_{(j+1)}]$  by a linear interpolation between  $\hat{m}_\theta(T_{(j)})$  and  $\hat{m}_\theta(T_{(j+1)})$ .

## SIMULATION STUDIES

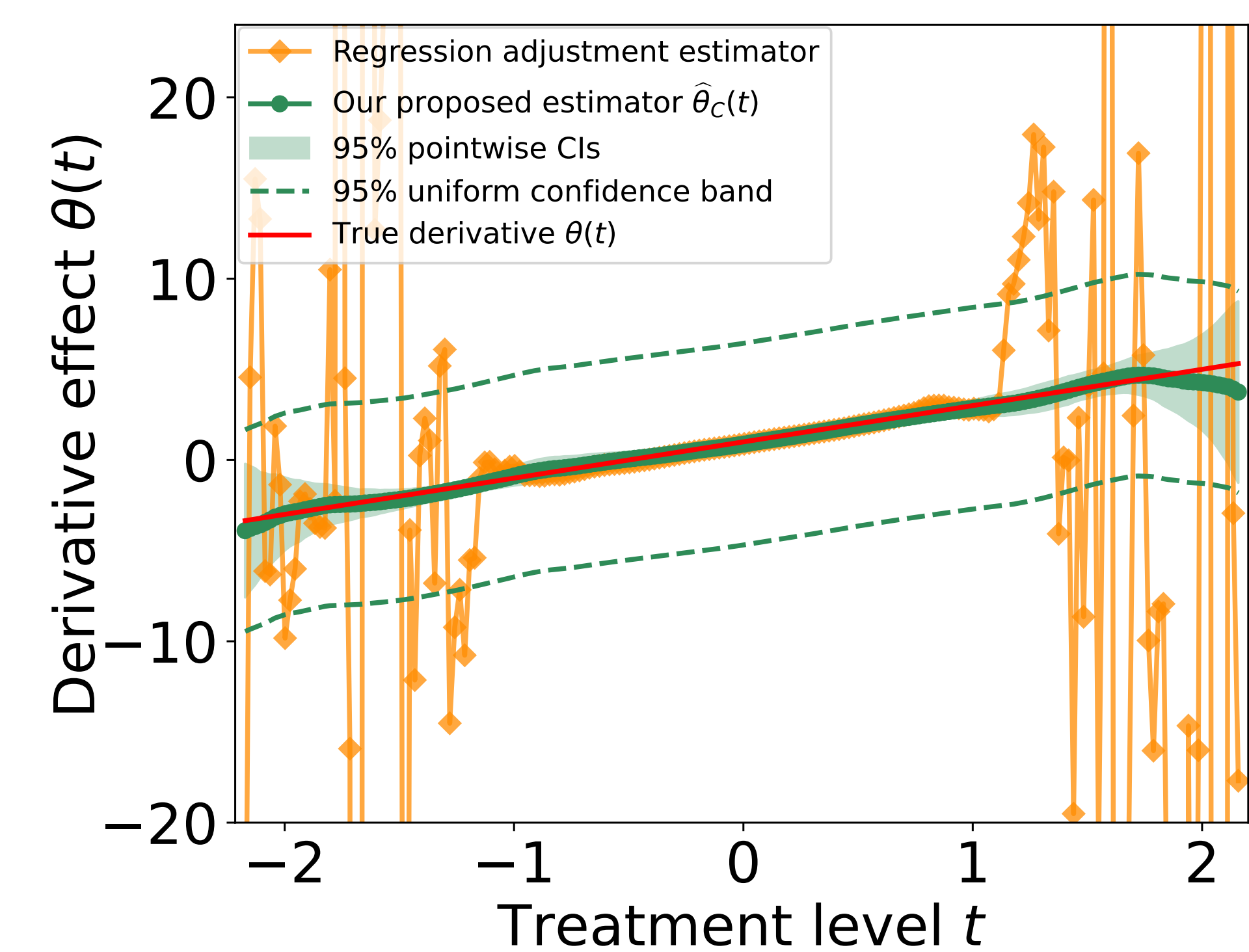
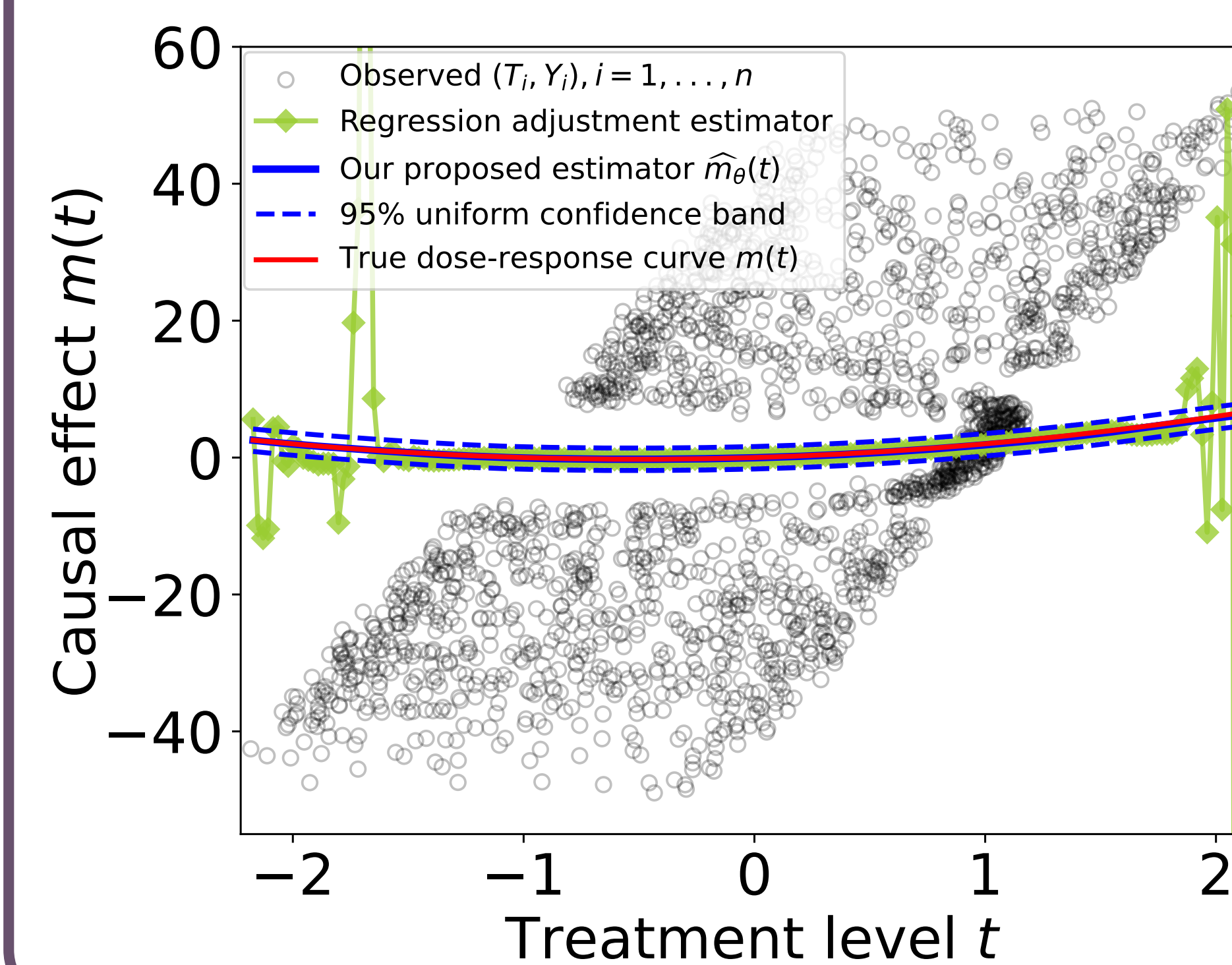
### • Single Confounder Model:

$$Y = T^2 + T + 1 + 10S + \epsilon, \quad T = \sin(\pi S) + E, \quad S \sim \text{Unif}[-1, 1] \subset \mathbb{R}, \quad E \sim \text{Unif}[-0.3, 0.3], \quad \text{and} \quad \epsilon \sim \mathcal{N}(0, 1).$$



### • Nonlinear Confounding Model:

$$Y = T^2 + T + 10Z + \epsilon, \quad T = \cos(\pi Z^3) + Z/4 + E, \quad Z = 4S_1 + S_2, \\ S = (S_1, S_2) \sim \text{Unif}[-1, 1]^2 \subset \mathbb{R}^2, \quad E \sim \text{Unif}[-0.1, 0.1], \quad \text{and} \quad \epsilon \sim \mathcal{N}(0, 1).$$



## EFFECT OF PM<sub>2.5</sub> ON CARDIOVASCULAR MORTALITY RATE (CMR)

The covariate vector  $\mathbf{S} \in \mathbb{R}^{10}$  includes spatical locations (longitude, latitude) and eight socioeconomic factors.

